# A String-Theoretic Introduction to Mirror Symmetry 

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## Warnings

These slides serve as a motivational introduction to mirror symmetry from a physical perspective. We will go through some basic concepts aimed at mathematical audiences. The logic flow is more chronological than pedagogical.

I am new to this subject, so mistakes and missings are inevitable.

# Table of Contents 

(1) Crash Course on String Theory
(2) Compactification
(3) Calabi-Yau Manifolds
(4) Mirror Symmetry

# Table of Contents 

(1) Crash Course on String Theory
(2) Compactification
(3) Calabi-Yau Manifolds
(4) Mirror Symmetry

## Principle of Least Action

## Definition (Action Functional)

Let $\mathcal{M}$ be the "space of configurations" of a physical system. The action functional is a linear map $S: \mathcal{M} \rightarrow \mathbb{R}$.

In classical mechanics, $\mathcal{M}$ is the space of piecewise smooth paths from $x$ to $y$ on a smooth manifold $M$.
In classical field theory, $\mathcal{M}$ is the space of sections of a vector bundle $E$ over the spacetime manifold $(M, g)$.
We need a well-behaved measure on $\mathcal{M}$ to perform calculus of variations and integrations. This is usually not well-defined, but physicists just assume it.

## Principle of Least Action

## Proposition (Principle of Least Action)

The trajectory of a system is the one which extremise the action: $\delta S=0$.

In classical mechanics, the action arises as the integral of the Lagrangian:

$$
S=\int_{t_{0}}^{t_{1}} L\left(q_{a}, \dot{q}_{a}, t\right) \mathrm{d} t
$$

The principle of least action is equivalent to the Euler-Lagrange equations ("equations of motions"):

$$
\frac{\mathrm{d}}{\mathrm{~d} t} \frac{\partial L}{\partial \dot{q}_{a}}-\frac{\partial L}{\partial q_{a}}=0,
$$

where $\left(q_{1}, \ldots, q_{n}\right)$ is a set of coordinates on $M$.

## Principle of Least Action

## Proposition (Principle of Least Action)

The trajectory of a system is the one which extremise the action: $\delta S=0$.

In classical field theory, the action arises as the integral of the Lagrangian density:

$$
S=\int_{M} \mathcal{L}\left(\varphi_{\alpha}, \partial_{a} \varphi_{\alpha}\right){\mathrm{d} \operatorname{vol}_{g}=\int_{\mathbb{R}^{1}, d-1}}^{\mathcal{L} \sqrt{-\operatorname{det} g} \mathrm{~d}^{n} x . . . . . . .}
$$

The Euler-Lagrange equations:

$$
\sum_{a} \frac{\partial}{\partial x^{a}} \frac{\partial \mathcal{L}}{\partial\left(\partial_{a} \varphi_{\alpha}\right)}-\frac{\partial \mathcal{L}}{\partial \varphi_{\alpha}}=0
$$

## Path Integral Formalism

Now we move from classical to quantum! In the path integral formalism, the primary object is the partition function:

$$
Z:=\int_{\mathcal{M}} \mathcal{D}[\gamma] \mathrm{e}^{\mathrm{i} S(\gamma) / \hbar}
$$

where $\mathcal{D}[\gamma]$ is a well-behaved measure on $\mathcal{M}$ (which, unfortunately, does not exist in general. This is one of the most notable mathematical difficulties of quantum field theory.)

In the classical limit $\hbar \rightarrow 0$, only the classical solution such that $\delta S=0$ contributes to the partition function.

An observable $O$ is an operator-valued distribution on $\mathcal{M}$ with the expectation:

$$
\langle O\rangle:=\int_{\mathcal{M}} \mathcal{D}[\gamma] O(\gamma) \mathrm{e}^{\mathrm{i} S(\gamma) / \hbar}
$$

## Polyakov Action

A string is a 1-dimensional object in the space. It traces out a 2-dimensional surface (the "worldsheet") in the spacetime M. So mathematically, string theory is about (the quantisation of) the embedding $X: \Sigma \rightarrow M$ of a Lorentzian surface into a $d$-dimensional Lorentzian manifold.

## Definition (Polyakov Action)

The classical bosonic string is described by the Polyakov action:

$$
S[X, h]=-\frac{1}{4 \pi \alpha^{\prime}} \int_{\Sigma} \mathrm{d}^{2} \sigma \sqrt{-\operatorname{det} h} h^{\alpha \beta} \partial_{\alpha} X^{\mu} \partial_{\beta} X^{\nu} g_{\mu \nu}
$$

where $h, g$ are the metrics on $\Sigma$ and $M$ respectively, and $X=\left(X^{\mu}\right)$ are the coordinates of $M$.

## Supersymmetry

Slogan:

| bosonic fields | fermionic fields |
| :---: | :---: |
| even variables | odd variables |
| ("c-numbers") | ("Grassmann numbers") |
| commutator $[a, b]=a b-b a$ | anti-commutator $\{a, b\}=a b+b a$ |

$$
\begin{aligned}
\text { ungraded Lie algebra } & \rightarrow \mathbb{Z} / 2 \text {-graded Lie algebra } \\
& \text { ("supersymmetric algebra") }
\end{aligned}
$$

Supersymmetric scalar multiplet: (scalar fields $X^{\mu}$, fermions $\psi^{\mu}$ ); Supergravity multiplet: (frame fields $e_{\alpha}^{a}$, gravitini $\chi_{\alpha}$ ).

## Ramond-Neveu-Schwarz Strings

Bosonic string $+N=1$ worldsheet supersymmetry $=$ RNS string.

## Proposition (RNS String Action)

The RNS string (fixed to superconformal gauge) is described by the action

$$
S=-\frac{1}{8 \pi} \int_{\Sigma} \mathrm{d}^{2} \sigma\left(\frac{2}{\alpha^{\prime}} \partial_{\alpha} X^{\mu} \partial^{\alpha} X^{\nu}+2 \mathrm{i} \bar{\psi}^{\mu} \rho^{\alpha} \partial_{\alpha} \psi^{\nu}\right) g_{\mu \nu}
$$

The action is invariant under the supersymmetric transformation:

$$
\begin{aligned}
\sqrt{\frac{2}{\alpha^{\prime}}} \delta_{\epsilon} X^{\mu} & =\mathrm{i} \bar{\epsilon} \psi^{\mu} \\
\delta_{\epsilon} \psi^{\mu} & =\sqrt{\frac{2}{\alpha^{\prime}}} \frac{1}{2} \rho^{\alpha} \partial_{\alpha} X^{\mu} \epsilon
\end{aligned}
$$

## Conformal Field Theory

The classical string action is Weyl invariant:

$$
h \mapsto \Omega^{2} h
$$

So string theory is a 2 -dimensional conformal field theory! The stress-energy tensor is traceless: $\operatorname{tr} T=0$.

After quantisation, Weyl invariance must be preserved:

$$
\langle\operatorname{tr} T\rangle=-\frac{c}{12} R \quad \text { (worldsheet scalar curvature) }
$$

So central charge $c=0$.
After massaging operator product expansions...

$$
c=d-10 \Longrightarrow d=10
$$

Conformal field theory tells us that superstrings live in 10 spacetime dimensions!!! Needs compactification of 6 extra dimensions to get real-world physics. See later.

## Conformal Field Theory

For closed strings, the periodic boundary condition on $\psi^{\mu}$ :

$$
\begin{aligned}
\psi^{\mu}(\sigma) & =+\psi^{\mu}(\sigma+\ell), & & \text { Ramond sector } \\
\psi^{\mu}(\sigma) & =-\psi^{\mu}(\sigma+\ell), & & \text { Neveu-Schwarz sector }
\end{aligned}
$$

Two independent spinors $\psi_{+}^{\mu}\left(\sigma^{+}\right), \psi_{-}^{\mu}\left(\sigma^{-}\right)$, so 4 types of closed strings: (R,R), (NS,NS), (R,NS), (NS,R).
$N=1$ super-Virasoro algebra:

$$
\begin{aligned}
{\left[L_{m}, L_{n}\right] } & =(m-n) L_{m+n}+\frac{c}{12} m\left(m^{2}-1\right) \delta_{m,-n} \\
{\left[L_{m}, G_{r}\right] } & =\left(\frac{m}{2}-r\right) G_{m+r} \\
\left\{G_{r}, G_{s}\right\} & =2 L_{r+s}+\frac{c}{12}\left(4 r^{2}-1\right) \delta_{r,-s}
\end{aligned}
$$

Ramond sector: $r, s \in \mathbb{Z}$; Neveu-Schwarz sector: $r, s \in \mathbb{Z}+\frac{1}{2}$.

## Working towards Superstring Theories

Recall that in bosonic string theory, critial dimension $d=26$; and the ground state is tachyonic ( $m^{2}<0$ ).

For superstring with worldsheet as a Riemann surface:
Modular invariance \& Vanishing of one-loop partition function

$$
\begin{gathered}
\text { GSO projection } \\
\Downarrow
\end{gathered}
$$

Tachyon-free \& Spacetime supersymmetry $\mathcal{N}=2$
Type IIA superstring theory (Non-chiral)

Type IIB superstring theory (Chiral)

## The Landscape of String Dualities



Type I

# Table of Contents 

(1) Crash Course on String Theory
(2) Compactification
(3) Calabi-Yau Manifolds
(4) Mirror Symmetry

## Compactification

Superstring theory works in 10 dimensions, but our physical world has only 4 dimensions. We would like to factor the spacetime as

$$
\mathbb{R}^{1,3} \times M_{6}
$$

where $M_{6}$ is a 6 -dimensional compact Riemannian manifold of length scale $\sim 10^{-35} \mathrm{~m}$.

Even though we do not observe $M_{6}$, the geometry of it actually determines the physics in the Minkowski space $\mathbb{R}^{1,3}$ !

Toroidal compactification: $M_{6}=T^{6}$.
All supersymmetries preserved $\rightarrow$ phenomenologically unfavourable.
Calabi-Yau compactification of heterotic strings: $M_{6}=\mathrm{CY}_{3}$.
$\mathcal{N}=1$ minimal supersymmetric standard model (MSSM)!
There are simply too many choices of $M_{6}$ for string theory to make physical predictions. This is why string theory is not considered as a part of physics by many people.

## Naive Example: Toroidal Compactification

Consider the compactification $M^{d+1}=M^{d} \times S^{1}$ :

$$
x^{d} \sim x^{d}+2 \pi R w .
$$

$R \in R$ is the radius of the circle $S^{1} ; w \in \mathbb{Z}$ is the winding number.
Slogan: Gravity in $(d+1)$-dimensions produces electromagnetism in $d$-dimensions.

Factorisation of metric:
$G=\sum_{M, N=0}^{d} g_{M N} \mathrm{~d} x^{M} \mathrm{~d} x^{N}=\sum_{\mu, \nu=0}^{d-1} g_{\mu \nu} \mathrm{d} x^{\mu} \mathrm{d} x^{\nu}+g_{d d}\left(\mathrm{~d} x^{d}+\sum_{\mu=0}^{d-1} A_{\mu} \mathrm{d} x^{\mu}\right)^{2}$.
Coordinate change $x^{d} \mapsto x^{d}+\lambda\left(x^{\mu}\right)$ produces gauge transformation $A_{\mu} \mapsto A_{\mu}-\partial_{\mu} \lambda$.
"Kaluza-Klein Reduction". $A_{\mu}$ : KK gauge boson.

## Naive Example: Toroidal Compactification

Scalar field $\phi$ in $(d+1)$-dimensions has the mode expansion:

$$
\phi\left(x^{M}\right)=\sum_{n \in \mathbb{Z}} \phi_{n}\left(x^{\mu}\right) \mathrm{e}^{\mathrm{i} n x^{d} / R}
$$

The momentum $p_{d}=n / R$ is quantised.
Mass for bosonic string:

$$
m^{2}=\frac{n^{2}}{R^{2}}+\frac{w^{2} R^{2}}{\alpha^{\prime 2}}+\frac{2}{\alpha^{\prime}}(N+\widetilde{N}-2), \quad N-\widetilde{N}=n w
$$

T-duality:

$$
R \leftrightarrow \frac{\alpha^{\prime}}{R}, \quad n \leftrightarrow w .
$$

Also Type IIA $\leftrightarrow$ Type IIB.

## Naive Example: Toroidal Compactification

Now consider compactification $M^{d+D}=M^{d} \times T^{D}, T^{D}:=\mathbb{R}^{D} / 2 \pi \Lambda_{D}$. For modular invariance the lattice $\Lambda_{D}$ must be self-dual: $\Lambda_{D}=\Lambda_{D}^{*}$.

KK reduction $\Longrightarrow$ Gauge boson $A_{\mu}, 2$-form $B_{m n}$. $B$-field: "massless scalar degrees of freedom contributed by the internal 2-form" ...

T-duality:

$$
\frac{1}{\alpha^{\prime}}(\boldsymbol{g}+\boldsymbol{b}) \leftrightarrow \alpha^{\prime}(\boldsymbol{g}+\boldsymbol{b})^{-1}, \quad \boldsymbol{n} \leftrightarrow \boldsymbol{w}
$$

Moduli space:

$$
\frac{\mathrm{O}(D, D)}{\mathrm{O}(D) \times \mathrm{O}(D)} / \mathrm{O}(D, D ; \mathbb{Z})
$$

2-torus: $T^{2}=\mathbb{R}^{2} /\left(\mathbb{Z} e_{1}+\mathbb{Z} e_{2}\right) . g_{i j}:=e_{i} \cdot e_{j}$.
Complexified Kähler modulus: $T:=\frac{1}{\alpha^{\prime}}(B+\mathrm{i} \sqrt{\operatorname{det} g})=T_{1}+\mathrm{i} T_{2}$.
Complex structure modulus:
$U:=\frac{\left\|e_{2}\right\|}{\left\|e_{1}\right\|} \mathrm{e}^{\mathrm{i} \varphi\left(e_{1}, e_{2}\right)}=\frac{g_{12}+\mathrm{i} \sqrt{\operatorname{det} g}}{g_{11}}=U_{1}+\mathrm{i} U_{2}$.

$$
\left(g_{i j}\right)=\alpha^{\prime} \frac{T_{2}}{U_{2}}\left(\begin{array}{cc}
1 & U_{1} \\
U_{1} & |U|^{2}
\end{array}\right) .
$$

T-duality: $\left(n_{1}, n_{2}, w_{1}, w_{2}\right) \leftrightarrow\left(-w_{1}, n_{2},-n_{1}, w_{2}\right) ; \quad T \leftrightarrow U$.
This is a prototype of mirror symmetry, where the complex structure and the Kähler structure interchanges under the mirror transformation.

# Table of Contents 

(1) Crash Course on String Theory
(2) Compactification
(3) Calabi-Yau Manifolds
(4) Mirror Symmetry

## Special Holonomy

Compactification: $\mathbb{R}^{1,3} \times M_{6}$. Why Calabi-Yau?

```
Ricci-flat: R}\mp@subsup{R}{mn}{}=0\mathrm{ . (Think of vacuum solutions of Einstein
equation.)
```

$\mathrm{SU}(3)$ holonomy.

## Definition (Curvature)

Let $(M, g)$ be a Riemannian/Lorentzian manifold with Levi-Civita connection $\nabla$. The Riemann curvature is given by $R_{a b c}{ }^{d} \partial_{d}=$ $\left[\nabla_{a}, \nabla_{b}\right] \partial_{c}$. The Ricci curvature is given by $R_{a b}:=R_{c a b}{ }^{c}$.

## Definition (Holonomy Group)

Let $(M, g)$ as above. The holonomy group $\operatorname{Hol}_{x}(\nabla)$ based at $x \in M$ is the group generated by the parallel transports $P_{\gamma}$, where $\gamma$ is a loop in $M$ based at $x$.

Compactification: $\mathbb{R}^{1,3} \times M_{6}$. Why Calabi-Yau?
Ricci-flat: $R_{m n}=0$.
$\mathrm{SU}(3)$ holonomy.
Decomposition of Weyl representation under $\mathrm{SO}(1,9) \rightarrow \mathrm{SO}(1,3) \times \mathrm{SO}(6):$

$$
\mathbf{1 6}=\mathbf{2}_{L} \otimes \overline{\mathbf{4}} \oplus \mathbf{2}_{\boldsymbol{R}} \otimes 4
$$

Further decomposition of $\mathbf{4}$ of $\mathfrak{s o}(6) \cong \mathfrak{s u}(4)$ if $M_{6}$ has a $\mathrm{SU}(3)$-structure:

$$
\mathbf{4}_{\mathfrak{s u}(4)}=(\mathbf{1} \oplus \mathbf{3})_{\mathfrak{s u}(3)} .
$$

The singlet state of $\mathfrak{s u}(3)$ is a covariantly constant spinor of $M_{6}$, i.e. $\nabla_{m} \epsilon=0$. This produces $\mathcal{N}=1$ supersymmetry in $d=4$.
Side effect: $M_{6}$ is Ricci-flat. (Exercise: try to prove this~)

## Kähler Manifolds

Slogan: A Kähler manifold is the one with compatible Riemannian, complex, and symplectic strctures, encoded by:

$$
\omega(X, Y)=g(J X, Y)
$$

where:
$\omega \in \Gamma\left(\bigwedge^{2} \mathrm{~T}^{*} M\right)$ is a symplectic form;
$J \in \Gamma(\operatorname{End}(T M))$ is a complex structure $\left(J^{2}=-\mathrm{id}\right)$;
$g \in \Gamma\left(\mathrm{~S}^{2} \mathrm{~T}^{*} M\right)$ is a Riemannian metric.
Any two of $(\omega, J, g)$ determines the third one.
Local expression:

$$
\omega=\mathrm{i} g_{\mu \bar{\nu}} \mathrm{d} z^{\mu} \wedge \mathrm{d} \bar{z}^{\nu}, \quad g_{\mu \nu}=g_{\overline{\mu \nu}}=0
$$

## Hodge Theory

Kähler manifolds are a special class of complex manifolds (real manifolds with an integrable almost complex structure J.)

Exterior differential splits into holomorphic \& anti-holomorphic parts:

$$
\mathrm{d}=\partial+\bar{\partial}
$$

de Rham cohomology $\mathrm{H}_{\mathrm{dR}}^{n}(M ; \mathbb{C})=\bigoplus_{p+q=n} \mathrm{H}^{p, q}(M)$
Dolbeault cohomology $\mathrm{H}^{p, q}(M)=\mathrm{H}^{q}\left(M, \Omega_{M}^{p}\right)$.

$$
\partial: \mathrm{H}^{p, q}(M) \rightarrow \mathrm{H}^{p+1, q}(M) ; \quad \bar{\partial}: \mathrm{H}^{p, q}(M) \rightarrow \mathrm{H}^{p, q+1}(M) .
$$

Hodge numbers: $h^{p, q}(M):=\operatorname{dim}_{\mathbb{C}} \mathrm{H}^{p, q}(M)$.

Serre duality:

$$
\mathrm{H}^{p, q}(M) \cong \mathrm{H}^{n-q, n-p}(M) .
$$

Hodge star:

$$
\mathrm{H}^{p, q}(M) \cong \mathrm{H}^{n-p, n-q}(M)
$$

Complex conjugation:

$$
\mathrm{H}^{p, q}(M) \cong \mathrm{H}^{q, p}(M)
$$

Hodge diamond:


There are a lot of different and inequivalent definitions of a Calabi-Yau manifold.

## Definition (Calabi-Yau Manifolds)

Let $M$ be a $2 n$-dimensional compact Kähler manifold. We say that $M$ is Calabi-Yau, if it satisfies any of the following conditions:

1. $M$ has vanishing first Chern class $c_{1}(M)$;
2. $M$ admits a Ricci-flat Kähler metric;
3. $M$ has trivial canonical bundle $K_{M}=\bigwedge^{n} \Omega_{M}$;
4. $M$ admits a Kähler metric with holonomy contained in $\mathrm{SU}(n)$.
5. $M$ has a unique nowhere vanishing holomorphic $n$-form.

The conditions satisfy $(1) \Longleftrightarrow(2) \Longleftrightarrow(3) \Longleftrightarrow(4) \Longleftrightarrow(5)$. They are all equivalent if $M$ is simply connected.

The hard part is $(1) \Longrightarrow(2)$, known as the Calabi conjecture, proven by Yau in 1978.

## Calabi-Yau Manifolds

## Definition (Physicists' Calabi-Yau Manifolds)

Let $M$ be a $2 n$-dimensional compact Kähler manifold. We say that $M$ is Calabi-Yau, if $M$ admits a Kähler metric with holonomy exactly equal to $\mathrm{SU}(n)$.

Hodge numbers:

$$
h^{0,0}=1, \quad h^{n, 0}=1, \quad h^{i, 0}=0 \text { for } 0<i<n .
$$

So for a Calabi-Yau 3-fold, the only independent Hodge numbers are $h^{1,1}$ and $h^{1,2}$.

Euler characteristic $\chi\left(\mathrm{CY}_{3}\right)=2\left(h^{1,1}\left(\mathrm{CY}_{3}\right)-h^{1,2}\left(\mathrm{CY}_{3}\right)\right)$.

## Mirror Calabi-Yau 3-folds

$$
\begin{aligned}
& h^{0,0}=1
\end{aligned}
$$

$$
\begin{aligned}
& h^{3,1}=0 \quad h^{2,2}=h^{1, \AA} \quad h^{1,3}=0
\end{aligned}
$$

$$
\begin{aligned}
& \text { complex conjugation }
\end{aligned}
$$

Mirror pair $\left(X, X^{\vee}\right)$ :

$$
h^{1,1}(X)=h^{1,2}\left(X^{\vee}\right), \quad h^{1,2}(X)=h^{1,1}\left(X^{\vee}\right) .
$$

## Calabi-Yau Moduli Space

Infinitesmal deformation of the metric $g \mapsto g+\delta g$ preserving Ricci-flatness.

Lichnerowicz equation:

$$
\Delta_{L} \delta g_{\mu \nu}:=\nabla^{\rho} \nabla_{\rho} \delta g_{\mu \nu}+2 R_{\mu}{ }^{\rho}{ }_{\nu}{ }^{\sigma} \delta g_{\rho \sigma}=0
$$

1. Mixed indices $\delta g_{i \bar{\jmath}}$ :

$$
(\Delta \delta g)_{i \bar{\jmath}}=0
$$

So $\delta g_{i \bar{\jmath}}$ are components of a $(1,1)$-form.

$$
\delta g_{i \bar{\jmath}}=\sum_{\alpha=1}^{h^{1,1}} \widetilde{t}^{\alpha} b_{i \bar{\jmath}}^{\alpha}
$$

where $\widetilde{t^{\alpha}} \in \mathbb{R}$ are the Kähler moduli, which spans the Kähler cone.

## Calabi-Yau Moduli Space

Infinitesmal deformation of the metric $g \mapsto g+\delta g$ preserving Ricci-flatness.

Lichnerowicz equation:

$$
\Delta_{L} \delta g_{\mu \nu}:=\nabla^{\rho} \nabla_{\rho} \delta g_{\mu \nu}+2 R_{\mu}{ }^{\rho}{ }_{\nu}{ }^{\sigma} \delta g_{\rho \sigma}=0
$$

1. Combining with the deformation of $B$-field:

$$
\left(\mathrm{i} \delta g_{i \bar{\jmath}}+\delta B_{i \bar{\jmath}}\right) \mathrm{d} z^{i} \wedge \mathrm{~d} \bar{z}^{j}=\sum_{\alpha=1}^{h^{1.1}} t^{\alpha} b_{i \bar{\jmath}}^{\alpha}
$$

Now $t^{\alpha} \in \mathbb{C}$ are complexfied Kähler moduli.

## Calabi-Yau Moduli Space

Infinitesmal deformation of the metric $g \mapsto g+\delta g$ preserving Ricci-flatness.

Lichnerowicz equation:

$$
\Delta_{L} \delta g_{\mu \nu}:=\nabla^{\rho} \nabla_{\rho} \delta g_{\mu \nu}+2 R_{\mu}{ }^{\rho}{ }_{\nu}{ }^{\sigma} \delta g_{\rho \sigma}=0
$$

2. Pure indices $\delta g_{\bar{\imath}}$ :

$$
\Delta_{\bar{\partial}} \delta g^{i}=0, \quad \delta g^{i}:=g^{i \bar{k}} \delta g_{\bar{k} \bar{\jmath}} \mathrm{~d} \bar{z}^{\bar{\jmath}}
$$

$\delta g^{i}$ is a $\mathrm{T}_{M}:=\mathrm{T}^{1,0} M$-valued ( 0,1 )-form.

$$
\mathrm{H}_{\bar{\partial}}^{0,1}\left(M, \mathrm{~T}_{M}\right) \cong \mathrm{H}^{1}\left(M, \mathrm{~T}_{M}\right) \cong \mathrm{H}^{2,1}(M), \text { so }
$$

$$
\Omega_{i j k} \delta g_{\bar{l}}^{k}=\sum_{a=1}^{h^{2,1}} t^{\alpha} b_{i j \bar{l}}^{\alpha}
$$

where $t^{\alpha} \in \mathbb{C}$ are the complex structure moduli.

# Table of Contents 

(1) Crash Course on String Theory
(2) Compactification
(3) Calabi-Yau Manifolds
(4) Mirror Symmetry

## Massless Spectra of Type IIA \& Type IIB Theories

## Type IIA on $X \longleftrightarrow$ Type IIB on $X^{\vee}$ !

Table 14.1 Massless spectrum of the type II theories on $\mathrm{CY}_{3}$

| Multiplet | Component fields | Multiplicity |
| :---: | :---: | :---: |
| Type IIA |  |  |
| Gravity <br> Hyper <br> Hyper <br> Vector |  | 1 <br> 1 <br> $h^{2,1}$ <br> $h^{1,1}$ |
| Type IIB |  |  |
| Gravity <br> Hyper <br> Hyper <br> Vector |  | 1 <br> 1 <br> $h^{1,1}$ $h^{2,1}$ |

